1. Molecular Robots and the Lipid Bilayer Platform

Molecular robots have recently emerged based on biomolecules and biochemical processes. Approximately 30 years ago, a self-constructing machine, a so-called “assembler,” was originally proposed by Drexler. Based on the idea of an assembler, molecular machines that operate autonomously have been developed using DNA or RNA. For example, DNA walkers move autonomously, on the basis of energy supplied from the hybridization of fuel oligonucleotides, from one binding site to another on a DNA-modified surface. Rothemund has also proposed a method by which DNA molecules can be folded into any desired two-dimensional shape to make “DNA origami.” In the field of synthetic chemistry, nanosized machines such as motors and ratchets have been developed based on organic or supramolecular chemistry. This was viewed as ground-breaking technology and the pioneers have since been honored with the Nobel Prize in Chemistry 2016.

Inspired by the idea of a molecular assembler, molecular robotics, which involves construction with a much higher dimension of assembly, was proposed in 2014. Molecular robots are composed of sensors, calculators, and actuators that are all implemented in liposomes or hydrogels. White blood cells, the most imageable example, senses the chemical signals secreted from a target bacterium, calculates the direction and length between the target and itself, and moves toward the signal source by chemotaxis. These accomplished functions are integrated in a micron-sized body surrounded with a bilayer lipid membrane (BLM). Sato et al. reported the development of a sophisticated molecular robot prototype in 2017. Their developed amoeba-type robot has light-induced DNA clutches for sensors and kinesin-microtubule proteins as actuators, all integrated in a cell-sized liposome. Light irradiation acts as a trigger for the release of the signal molecules and disengagement of the DNA clutches to change the shape of the liposome.

The fabrication process used for existing mechanical robots is viewed as a blueprint for the manufacture of these molecular robots. In the case of humanoid robots, the arms and legs are manufactured individually and then assembled. Similarly, individual fabrication would be a straightforward process in the manufacturing of molecular robots. Hence, a prototyping factory is required, as well as an industrial manufacturing process.

In this Minireview, I focus on manufacturing the body of the molecular robot using BLM with membrane receptors (Figure 1). BLM is the ideal material for the body of molecular robots because it is naturally biocompatible and can host receptor proteins. In addition, physical dynamics such as membrane fusion and endo-or exocytosis, such as molecular uptake processes, are useful for the interface of the robots. We previously developed a high-throughput planar BLM (pBLM) system that will be a powerful tool for the manufacturing of the lipid body of molecular robots. A pBLM is generally used as the ion current measurement of an ion channel or pore-forming proteins. Because the reproducibility and stability of pBLMs are conventionally insufficient, various methods have been proposed to overcome this, primarily using microfluidic technology. The most promising method is the droplet contact method, in which two microdroplets surrounding the
In the last three decades, synthetic chemists have

Conceptual illustration of a molecular robot. The body consists of

lilipat monolayer are brought into contact and a stable and reproducible pBLM is formed at the droplet interface, as the droplet–interface bilayer. This method is simple and rapid, and the formed pBLM is extremely stable. Based on this method, several high-throughput pBLM formation methods have been proposed and applied to large-scale measurement of ion channels or nanopore measurements.[16–18]

In the following section, two recent efforts are introduced that attempted 1) to use a synthetic ion channel as the artificial receptor protein, and 2) autonomous sensing and calculation using DNA computing with nanopore technology using a high-throughput pBLM system. Synthetic channels are potential candidates for the sensor sections of molecular robots.

DNA computing technology with nanopore proteins will be able to connect the sensor and intelligence functions.

2. Synthetic Ion Channels and Transport Control at the Lipid Bilayer Membrane

Receptor proteins sense specific molecules in the cell membrane. When the ligand molecule binds to a receptor, the receptor senses the binding and produces a signal that is transmitted downstream to control ion transport through ion channels, as it cascades. Furthermore, pore-forming proteins play a key role in the transportation of molecules with the gradient of membrane potential or the substrate concentration. Artificial ion channels or pores have been created using synthetic chemistry to mimic the structure or function of natural proteins.[19,20] In the last three decades, synthetic chemists have proposed various compounds that actively exhibit ion channel structures and functions.[21] As part of the design, chemists try to add functions such as pore size, ion or substitute selectivity, and voltage or ligand gating. In the early studies, researchers imitated natural compounds, such as valinomycin or gramicidin, for the structural framework of synthetic channels (Figure 2a). Valinomycin is a macrocyclic polypeptide used in the transport of potassium, as an antimicrobial peptide. Gramicidin is also a polypeptide and forms a β-helix structure in the lipid monolayer,[22] within the bilayer, two gramicidin molecules form an end-to-end dimer, which in turn forms a transmembrane structure in the bilayer. These macrocyclic or dimer structures have been modeled for the design of synthetic channels, and chemists synthesized the mimicking structure using synthetic peptides or macromolecules. More recently, other functional materials such as DNA origami and carbon nanotubes have been proposed as potential candidates for artificial ion channels.[19,23,24]

One of the most sought after properties is ion selectivity for Na⁺, K⁺, Ca²⁺, Cl⁻, and other ions. Most studies have focused on synthesis of the channel structure in the lipid membrane, and assessed the ion selectivity. Among them, the first report of a selective channel was for K⁺ ions.[25] In nature, potassium-channel proteins use a selective filter that has five amino acids, TVGYG, within each of the four subunits. The hydrated K⁺ ion is dehydrated by interacting with these motifs, and then passes through the filter pore with high ion selectivity (Figure 2b).[26] Conversely, in the synthetic channels, the K⁺-selective filter is composed of an aromatic ring (primarily formed by four tyrosine residues) that provides a weak electric field, allowing complete dehydration of K⁺ ions, but not of Na⁺ ions.

In this system, the π electrons of the aromatic rings contribute to the lowering of the potential barrier for passage of K⁺ ions through attractive π-cation interactions (Figure 2c).[27] Following examination of K⁺ selectivity, the selection trend, for example, Li⁺ > Na⁺ > K⁺, is estimated in terms of alkali metal ions, as the Eisenman sequence.[22] The selectivity for other ions or molecules, such as halide ions, divalent ions, and ammonium ions has also been studied extensively by researchers. More recently, a de novo strategy from protein engineering

Figure 1. Conceptual illustration of a molecular robot. The body consists of a lipid bilayer with synthetic ion channels as the gate. DNA computing architecture is integrated inside the robot as the intelligence. (This illustration is used courtesy of Professor S. Murata of Tohoku University).
Other interesting strategies based on natural and synthetic ion channels have been proposed. These strategies typically involve the use of metal–organic frameworks (MOFs) that can transport ions across membranes and create a gradient. In experiments conducted, the artificial pump operated reversibly for two cycles of operation and drove rings against the concentration gradient, but the system did not conduct movement in the lipid membrane.

Controlling the open-close state (gating) of synthetic channels, by contrast, is very challenging. Most approaches utilize voltage gating: an early approach used by Fyles and co-workers and Kobuke and co-workers involved an asymmetrical structure with charged parts at one of the termini in the transmembrane molecules. Kawano, Furukawa and co-workers have also attempted to create gating-controllable synthetic channels. They focused on metal–organic scaffolds because of the tunability of the structure. Metal–organic frameworks have attracted substantial attention as porous materials, especially for adsorption or storage of gas molecules. Recently, Kim and co-workers investigated the capability of metal–organic molecules as synthetic ion channels. Following their study, we synthesized rhodium metal–organic polyhedrals (RhMOPs) that have two different lengths of alkoxy chains (C12 and C14) at the periphery for controlling the open-close state, called C12RhMOP and C14RhMOP. In addition, these RhMOP molecules showed two distinct channel conductance states because the Archimedean geometry of the MOP structure allows porous molecules to possess more than two different polygonal apertures and one internal cavity. Therefore, ions pass through the internal cavity of the RhMOP via either the square or the triangular aperture exposed to the aqueous phase in the lipid bilayer. The long alkyo chains at the periphery can facilitate interaction with lipid molecules, and the difference in the length enables modulation of its interaction such that it can alter the molecular dynamics, resulting in switching between the open–close states.
As described above, synthetic channels will be useful tools at the interface of the molecular robots and their external environment. This is because the selectivity of information, as ions or molecules, and controllability of the gating are absolutely imperative. The next step is regulation of these functions from external stimulation using light irradiation, magnetic fields, or electrical stimulation.

3. Nanopore Technology Meets DNA Computing and is Applied to Practical Sensing

Nanopores—pore-forming transmembrane proteins—are another strong candidate for the sensors of molecular robots. Sensing with nanopores has emerged as a method for single-molecule detection. This method works by applying an electric potential that causes single molecules to be passed through the nanopore. The change in the ionic current over time is recorded, potentially allowing the direct collection of information about individual molecules in terms of size and mobility (Figure 4a). Although this method can detect single molecules, the selectivity relies on the size compatibility between the nanopore and target molecules. An α-hemolysin (αHL), pore-forming toxin from Staphylococcus aureus, is commonly used as the biological nanopore. This protein has a 1.4 nm diameter pore that allows single-stranded DNA (ssDNA) to pass but blocks double-strand DNA (dsDNA), suggesting that the nanopore has precise size selectivity for DNA/RNA detection. DNA aptamers have also been applied as the molecular tag for selective detection because αHL cannot detect larger sized molecules (Figure 4c). Conversely, we have studied much larger nanopores from five different protein families for precise nanopore detection. Recently, a promising application of nanopore measurements for DNA sequencing has also resulted from ardent efforts, with a
nanopore sequencer being commercialized in 2015. To this end, because conventional nanopores are highly compatible for detecting oligonucleotides, we have attempted to integrate the nanopore method into DNA computing in order to connect the sensoria and the intelligence of the molecular robots.

We have attempted to perform NAND logic calculations in a four-droplet system and to detect the output DNA molecule using an αHL nanopore reconstituted in the droplet-interface bilayer (Figure 5a). This droplet system has two inputs, an operation droplet for calculations, and an output droplet. After calculating the two input DNAs, they pass through the αHL nanopore and are transferred from the calculation to the output droplet. In this operation, ssDNA translocation through the αHL nanopore signifies an output of 1, whereas absence of DNA translocation signifies an output of 0. Output DNA molecules are detected by αHL nanopores with single-molecule translocation, and the system was label-free. The operation is relatively faster (approximately 10 min) than the conventional method. Next, we attempted to integrate more complex operations into this nanopore-droplet system. This system functions as an AND gate with amplification and transcription from DNA to RNA, using T7 RNA polymerase (T7RP). To construct this system, we used two input DNAs and template DNA containing part of the T7RP promoter region, as shown in Figure 5b. For cases in which two input DNAs exist, defined as input (1 1), the two DNAs form a duplex that hybridizes with the template DNA. The T7RP polymerase binds to the promoter region and synthesizes a large amount of RNA as output 1. In the cases of inputs (0 0), (0 1), and (1 0), the input DNA cannot hybridize with the template DNA, resulting in an output of 0. In addition, this AND gate operation was simultaneously conducted using a parallel droplet device with a short period (Figure 5c). Integration of DNA logic gates into electrochemical devices is important to ensure that molecules containing output information, such as diagnostic results, can be processed as human-recognizable information. In the next step, the programmable system is applied to practical application, for example, cancer diagnosis using microRNA.

MicroRNAs (miRNAs) are noncoding, small, single-stranded RNAs. They are involved in the regulation of over 60% of human genes, and they play significant roles in physiological processes. Accumulated evidence has revealed that aberrant levels of miRNA expression in tissues or blood is associated with various human diseases such as cancers and cardiovascular diseases. Therefore, miRNA is an emerging class of clinically important biomarkers for early diagnosis. A landmark report on miRNA detection using αHL nanopore was presented by Gu and co-workers. They used an oligonucleotide probe that binds to the target miRNA and generates programmable current signatures in the nanopore measurements (Figure 6a).
Using this system, they were able to selectively detect miRNAs at sub-picomolar levels in samples obtained from lung cancer patients. Subsequently, they applied the method to multiple miRNA detection by using DNA and polyethylene glycol tags as the barcode. The system also represented the programmable nanopore currents from four lung-cancer-derived miRNAs. We also proposed a theranostics system, which involves the combination of diagnosis and therapy at the same time, using a nanopore-droplet device (Figure 6b). The proposed system includes autonomous diagnosis of cancers using miRNA (as the input molecule) and therapy for the tumor cells by a DNA antisense drug (as the output molecule). In the presence of miR-20a secreted from a small-cell lung cancer (SCLC), two programmable DNAs functioning as diagnostic molecules bind to the input miR-20a, and form a three-way junction structure. At that time, isothermal reactions with enzymes (a Klenow fragment as the polymerase and Nt.AlwI as the nicking enzyme) repeatedly occur to generate a DNA drug called oblimersen. The generated molecules were quantified by the translocation frequency of the nanopore measurement in real time (Figure 6c). The results of nanopore quantification showed that oblimersen was amplified more than 20-fold from the input miR-20a, which meets the dosage requirement for SCLC therapy. Based on these DNA computing techniques, we have recently reported an approach for detection of miRNA at ultra-low concentrations, in which the target miRNA is amplified from 1 fm to pm level and then nanopores with asymmetrical electrolyte condition are detected, which can increase the event frequency of miRNA translocation.

Combining nanopore and DNA computing technologies is useful for constructing smart and autonomous sensing at the interface region. The nanopore/DNA computing system will contribute to the construction of intelligent sensors for molecular robots.

4. Perspectives for Molecular Robots with Lipid Bilayers

This Minireview focused on functionalization of lipid bilayers embedded with synthetic ion channels or nanopores with DNA
logic operation. These functions or technologies of such molecular machines and autonomous systems have matured sufficiently that they can operate on their own. Regarding the synthetic ion channels, early studies focused on constructing a transmembrane structure mimicking natural ion channels. Then, the transport properties such as ion selectivity or gating probability were investigated. Although in most cases the functions were carried out in a single operation, the natural ion channels work in signal cascades, and ion transport can induce a biological reaction. In the next step, the synthetic ion channel will be loaded onto the interface of the molecular robot. DNA logic operations face a similar situation. Single operations such as AND, OR, and NAND can be combined to make sophisticated systems. Therefore, recent compelling work has shown that combining nanopore and DNA logic operations can result in a system that can be integrated into the body and interface with molecular robots.

Similar approaches can be found in synthetic biology and protocell studies, in which biological technologies such as gene manufacturing are used. It is envisaged that by fusing these technologies and science, in the future, microorganisms such as molecular robots will operate in living systems for diagnosis and therapy, in other environments for assessment or recovery, and in space for terraforming.

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**Conflict of Interest**

The author declares no conflict of interest.
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