

2015 International Conference on **Advanced Mechatronic Systems**



August 22-24, 2015
Beijing, China

CONFERENCE PROGRAM

Friday, August 21, 2015

14:30 - 17:30 Registration (Beijing Fujian Hotel, Beijing)
18:30 - 20:30 Welcome Reception (Beijing Fujian Hotel, Beijing)

Saturday, August 22, 2015

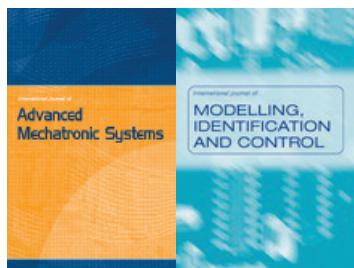
08:40-08:50	Opening Remarks	Main Conference Hall
08:50-09:50	Plenary Speech 1 (PS01)	Main Conference Hall
<p>Title: Intelligent Feedback Control for Operation of Complex Industrial Processes</p> <p>Speaker: Tianyou Chai, <i>Northeastern University, China</i> Chair: Hongnian Yu, <i>Bournemouth University, UK</i></p>		
09:50-10:00 <i>Break</i>		
10:00-11:00	Plenary Speech 2 (PS02)	Main Conference Hall
<p>Title: Modeling and Control of Hysteresis Nonlinearities in Smart Actuators</p> <p>Speaker: Chun-Yi Su, <i>Concordia University, Canada</i> Chair: Xinkai Chen, <i>Shibaura Institute of Technology, Japan</i></p>		
11:00-13:00	Lunch Break	
13:00-14:40 Parallel paper sessions		
Room No.01	Room No.02	Room No.03
SatM01 Renewable sources of energy	SatM02 Advanced intelligent control in robotics and mechatronics	SatM03 Optimization methods and applications I
14:40-14:50 <i>Break</i>		
14:50-16:30 Parallel paper sessions		
Room No.01	Room No.02	Room No.03
SatP01 Optimization methods and applications II	SatP02 Advanced nonlinear control in robotics	SatP03 Control of mechatronic systems I
16:30-16:40 <i>Break</i>		
16:40-18:20 (18:40) Parallel paper sessions		
Room No.01	Room No.02	Room No.03
SatE01 New developments on ESP	SatE02 Information processing	SatE03 Nonlinear systems modeling, control and applications

Sunday, August 23, 2015

08:50-09:50	Plenary Speech 3 (PS03)	Main Conference Hall
Title: Designed to Fail: Incorporating Kinematic Redundancy into Robotic Systems		
Speaker: Anthony A. Maciejewski, <i>Colorado State University, USA</i>		
Chair: J. X. Zhang, <i>Swinburne University of Technology, Australia</i>		
09:50-10:20	<i>Break</i>	
10:20-11:30	Poster Session	Main Conference Hall
11:30-13:00	<i>Lunch Break</i>	
13:00-14:40	Parallel paper sessions	
Room No.01	Room No.02	Room No.03
SunM01 Advanced control systems design - theory and applications	SunM02 Mechatronic systems analysis and control I	SunM03 Complex systems control and applications I
14:40-14:50	<i>Break</i>	
14:50-16:50	Parallel paper sessions	
Room No.01	Room No.02	Room No.03
SunP01 Control of mechatronic systems II	SunP02 Mechatronic systems analysis and control II	SunP03 Complex systems control and applications II
16:50-17:00	<i>Break</i>	
17:00-18:00	Plenary Panel Discussion	Main Conference Hall
Title: New Developments in Advanced Mechatronic Systems		
Organizers: Mingcong Deng, <i>Tokyo University of Agriculture and Technology, Japan</i> Hongnian Yu, <i>Bournemouth University, UK</i>		
18:30-20:30	Banquet (Beijing Fujian Hotel, Beijing)	

Monday, August 24, 2015

Technical Tour to The Great Wall of China
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2015 International Conference on Advanced Mechatronic Systems



August 22-24, 2015

Beijing, China



TECHNICAL PROGRAM

ICAMechS 2015

Friday, August 21, 2015

14:30 - 17:30

Registration

(Beijing Fujian Hotel, Beijing)

18:30 - 20:30

Welcome Reception

(Beijing Fujian Hotel, Beijing)

End of the 1st Day

ICAMechS 2015

Saturday, August 22, 2015

08:40 - 08:50

Main Conference Hall

Opening Remarks

08:50 - 09:50

Main Conference Hall

Plenary Speech 1

Intelligent Feedback Control for Operation of
Complex Industrial Processes

Tianyou Chai

Northeastern University, China

Chair: Hongnian Yu

Bournemouth Univ., UK

09:50 - 10:00

Break

10:00 - 11:00

Main Conference Hall

Plenary Speech 2

Modeling and Control of Hysteresis Nonlinearities
in Smart Actuators

Chun-Yi Su

Concordia University, Canada

Chair: Xinkai Chen

Shibaura Institute of Tech., Japan

11:00 - 13:00

Lunch Break

Early Afternoon Technical Sessions

13:00-14:40, Saturday, August 22, 2015

SatM01

Session Room No.01

Renewable sources of energy

Organized Session

Organizer: Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>
Chair: Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>
Co-Chair: Aihui Wang	<i>Zhongyuan Univ. of Tech., China</i>

13:00 - 13:20

SatM01-01

Cluster analysis on the service oriented alliance enterprise manufacturing resource

Yunxia Wang	<i>Nanjing Institute of Tech., China</i>
Shenghai Qiu	<i>Nanjing Institute of Tech., China</i>
Chengchong Gao	<i>Nanjing Institute of Tech., China</i>
Jun Wei	<i>Nanjing Institute of Tech., China</i>

13:20 - 13:40

SatM01-02

Performance and exhaust emissions of a turbocharged common rail DI diesel engine fueled with alcohol

Bin Xu	<i>Henan Univ. of Sci. and Tech., China</i>
Yibin Liu	<i>Henan Univ. of Sci. and Tech., China</i>
Jian Wu	<i>Henan Univ. of Sci. and Tech., China</i>
Chuang Li	<i>Henan Univ. of Sci. and Tech., China</i>
Weiwei Shang	<i>Henan Univ. of Sci. and Tech., China</i>
Zhihao Ma	<i>Henan Univ. of Sci. and Tech., China</i>

13:40 - 14:00

SatM01-03

Design and simulation of passive filter based on fundamental magnetic flux compensation

Qun Chen	<i>Henan Univ. of Sci. and Tech., China</i>
Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>

14:00 – 14:20

SatM01-04

Research on large supermarket fresh food supplier evaluation and selection based on SWOT-entropy weight fuzzy comprehensive model

Ying Yuan	<i>Henan Univ. of Sci. and Tech., China</i>
Yi Zhang	<i>Henan Univ. of Sci. and Tech., China</i>
Long Di	<i>Henan Univ. of Sci. and Tech., China</i>
Ganggang Wu	<i>Henan Univ. of Sci. and Tech., China</i>
Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>

14:20 – 14:40

SatM01-05

A novel outer rotor axial primary magnetic circuit permanent magnet generator

Ximei Li	<i>Henan Univ. of Sci. and Tech., China</i>
Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>
Dongliang Song	<i>Henan Univ. of Sci. and Tech., China</i>

SatM02

Session Room No.02

mechatronics

Organized Session

Organizer: Luige Vladareanu	<i>Romanian Acad., Romania</i>
Chair: Luige Vladareanu	<i>Romanian Acad., Romania</i>
Co-Chair: Zengguang Hou	<i>Chinese Acad. of Sci., China</i>

13:00 – 13:20

SatM02-01

Active training research of a lower limb rehabilitation robot based on constrained trajectory

Hongbo Wang	<i>Yanshan Univ., China</i>
Dong Zhang	<i>Yanshan Univ., China</i>
Hao Lu	<i>Yanshan Univ., China</i>
Yongfei Feng	<i>Yanshan Univ., China</i>
Peng Xu	<i>Yanshan Univ., China</i>
Razvan-Viorel Mihai	<i>Romanian Acad., Romania</i>
Luige Vladareanu	<i>Romanian Acad., Romania</i>

13:20 – 13: 40

SatM02-02

Fuzzy controller design of the wire feeder of invasive vascular interventional surgery robot

Hongbo Wang	<i>Yanshan Univ., China</i>
Shuaishuai Wang	<i>Yanshan Univ., China</i>
Wen Zhang	<i>Yanshan Univ., China</i>
Liyu Xie	<i>Yanshan Univ., China</i>
Xue Yang	<i>Univ. of Jinan, China</i>
Luige Vladareanu	<i>Romanian Acad., Romania</i>
Radu Munteanu	<i>Romanian Acad., Romania</i>

13:40 – 14:00

SatM02-03

Advanced intelligent walking robot control through sliding motion control and bond graphs methods

Ionel Alexandru Gal	<i>Romanian Acad., Romania</i>
Luige Vladareanu	<i>Romanian Acad., Romania</i>
Hongbo Wang	<i>Yanshan Univ., China</i>
Hongnian Yu	<i>Bournemouth Univ., UK</i>
Mingcong Deng	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

14:00 – 14:20

SatM02-04

Versatile intelligent portable robot platform for flexible robotic cells with AGV

Luige Vladareanu	<i>Romanian Acad., Romania</i>
Cristian Spirleanu	<i>Romanian Acad., Romania</i>
Mihaiela Iliescu	<i>Romanian Acad., Romania</i>
Hongnian Yu	<i>Bournemouth Univ., UK</i>
Mingcong Deng	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Weizhong Guo	<i>Shanghai Jiao Tong Univ., China</i>
Feng Gao	<i>Shanghai Jiao Tong Univ., China</i>

Advanced intelligent control in robotics and

14:20 – 14:40 SatM02-05

Haptic intelligent interfaces for NAO robot hand control

Octavian Melinte	Romanian Acad., Romania
Luige Vladareanu	Romanian Acad., Romania
Ligia Munteanu	Romanian Acad., Romania
Hongnian Yu	Bournemouth Univ., UK
Shuang Cang	Bournemouth Univ., UK
Zengguang Hou	Chinese Acad. of Sci., China
GuiBin Bian	Chinese Acad. of Sci., China
Hongbo Wang	Yanshan Univ., China

SatM03 Session Room No.03

Optimization methods and applications I

Regular Session

Chair: Shuhui Bi	Univ. of Jinan, China
Co-Chair: Huimin Xiao	Henan Univ. of Economics and Law, China

13:00 – 13:20 SatM03-01

Weak reachability of probabilistic boolean control networks

Zhiqiang Li	Henan Univ. of Economics and Law, China
Huimin Xiao	Henan Univ. of Economics and Law, China

13:20 – 13:40 SatM03-02

Oscillation criteria for a class of nonlinear impulsive parabolic system under Dirichlet boundary condition

Junhong Liu	Acad. of Armored Force Eng., China
Wenxue Liu	Acad. of Armored Force Eng., China
Lifeng Li	Acad. of Armored Force Eng., China
Qi Jin	Acad. of Armored Force Eng., China

13:40 – 14:00 SatM03-03

Operator-based left coprime factorization for nonlinear systems

Fazhan Tao	Tokyo Univ. of Agri. and Tech., Japan
Mingcong Deng	Tokyo Univ. of Agri. and Tech., Japan

14:00 – 14:20 SatM03-04

Passivity-based robust control for uncertain nonlinear feedback systems

Ni Bu	Qingdao Univ. of Sci. and Tech., China
Mingcong Deng	Tokyo Univ. of Agri. and Tech., Japan

14:20 – 14:40 SatM03-05

Correlated neural activity in spiking networks with topographic couplings

Jinli Xie	Univ. of Jinan, China
Qinjun Zhao	Univ. of Jinan, China
Jianyu Zhao	Univ. of Jinan, China

14:40 – 14:50

Break

Middle Afternoon Technical Sessions

14:50-16:30, Saturday, August 22, 2015

SatP01

Session Room No.01

Optimization methods and applications II

Regular Session

Chair: Guangdong Tian Northeast Forestry Univ., China

Co-Chair: Zongxiao Yang Henan Univ. of Sci. and Tech., China

14:50 – 15:10 SatP01-01

Scheduling of rescue vehicles to forest fires via multi-objective particle swarm optimization

Yaping Ren Northeast Forestry Univ., China

Guangdong Tian Northeast Forestry Univ., China

Mengchu Zhou New Jersey Institute of Tech., USA

15:10 – 15:30 SatP01-02

An effective VNSSA algorithm for the blocking flowshop scheduling problem with makespan minimization

Chaoyong Zhang Huazhong Univ. of Sci. & Tech., China

Zhanpeng Xie Huazhong Univ. of Sci. & Tech., China

Xinyu Shao Huazhong Univ. of Sci. & Tech., China

Guangdong Tian Northeast Forestry Univ., China

15:30 – 15:50 SatP01-03

Simulation modeling of shuttle racking system based on automod

Bingfeng Sang Beijing Univ. of Posts and Telecommunications, China

Yukun Liu Beijing Univ. of Posts and Telecommunications, China

15:50 – 16:10 SatP01-04

An expected value multi-objective optimization model to locate a vehicle inspection station

Guangdong Tian Northeast Forestry Univ., China

MengChu Zhou New Jersey Institute of Tech., USA

16:10 – 16:30 SatP01-05

Experimental study on nonlinear vibration control of an L-shape arm

Yanfeng Wu Tokyo Univ. of Agri. and Tech., Japan

Mingcong Deng Tokyo Univ. of Agri. and Tech., Japan

Longguo Jin Qingdao Technical College, China

SatP02

Session Room No.02

Advanced nonlinear control in robotics

Regular Session

Chair: Hongnian Yu	<i>Bournemouth Univ., UK</i>
Co-Chair: Yukinori Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
14:50 – 15:10	SatP02-01

The mechatronic system of eco-dolphin - a fleet of autonomous underwater vehicles

Hong Liu	<i>Embry-Riddle Aeronautical Univ., USA</i>
Xudong Shi	<i>Civil Aviation Univ. of China, China</i>
Junzhen Shao	<i>Embry-Riddle Aeronautical Univ., USA</i>
Qi Zhou	<i>Embry-Riddle Aeronautical Univ., USA</i>
Stacey Joseph-Ellison	<i>Embry-Riddle Aeronautical Univ., USA</i>
Johnathan Jaworski	<i>Embry-Riddle Aeronautical Univ., USA</i>
Ci Wen	<i>Embry-Riddle Aeronautical Univ., USA</i>

15:10 – 15:30

SatP02-02

Extended development of LinuxCNC for control of a delta robot

Feng Huo	<i>National Univ. of Singapore, Singapore</i>
Geoksoon Hong	<i>National Univ. of Singapore, Singapore</i>
Aunneow Poo	<i>National Univ. of Singapore, Singapore</i>

15:30 – 15:50

SatP02-03

Minimizing energy consumption in a U-shaped robotic assembly line

J Mukund Nilakantan	<i>Monash Univ. Malaysia, Malaysia</i>
S.G. Ponnambalam	<i>Monash Univ. Malaysia, Malaysia</i>
George Q Huang	<i>The Univ. of Hong Kong, China</i>

15:50 – 16:10

SatP02-04

Charged system search algorithm for robotic drill path optimization

G Kanagaraj	<i>Thiagarajar College of Eng., India</i>
S.G. Ponnambalam	<i>Monash Univ. Malaysia, Malaysia</i>
C.K. Loo	<i>Univ. of Malaya, Malaysia</i>

16:10 – 16:30

SatP02-05

Implementation of remotely controllable mobile robot system over mobile Ad-hoc Network

Mohammad Shahidul Hasan	<i>Staffordshire Univ., UK</i>
Hongnian Yu	<i>Bournemouth Univ., UK</i>

Regular Session

Chair: Shinji Wakui	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Co-Chair: Kazuyuki Ito	<i>Hosei Univ., Japan</i>

14:50 – 15:10

SatP03-01

An interpretation of unbalance vibration compensator for five-axes active magnetic bearing systems based on internal model principle

Taiki Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Shinji Wakui	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Yukinori Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

15:10 – 15:30

SatP03-02

Vibration suppression of galvano mirror considering whirling of shaft

Keisuke Nakade	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Taiki Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Shinji Wakui	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Yukinori Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

15:30 – 15:50

SatP03-03

A consideration of parameter identification of a linear stage using particle swarm optimization

Marino Watanabe	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Yukinori Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Shinji Wakui	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

15:50 – 16:10

SatP03-04

Development of a torque-sensorless viscometer for food processing applications

Seiji Hashimoto	<i>Gunma Univ., Japan</i>
Yuqi Jiang	<i>Gunma Univ., Japan</i>
Amat Basari	<i>Gunma Univ., Japan</i>
Wei Jiang	<i>Yangzhou Univ., China</i>

16:10 – 16:30

SatP03-05

Study on detection of earthquake using DI value and its application to switching control for air type anti-vibration apparatus

Masayuki Kubota	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Hirokazu Mineo	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Shinji Wakui	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Yukinori Nakamura	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

SatP03

Session Room No.03

Control of mechatronic systems I

16:30 - 16:40

Break

Last Afternoon Technical Sessions

16:40-18:20, Saturday, August 22, 2015

SatE01

Session Room No.01

New developments on ESP

Invited Session

Organizer: Jie Shi	<i>Univ. of Electro-Communications, Japan</i>
Chair: Jie Shi	<i>Univ. of Electro-Communications, Japan</i>
Co-Chair: Yan Yu	<i>Univ. of Electro-Communications, Japan</i>

16:40 - 17:00

SatE01-01

An overview of supplementary teaching materials for advanced EST students in japan

Yan Yu	<i>Univ. of Electro-Communications, Japan</i>
Jie Shi	<i>Univ. of Electro-Communications, Japan</i>

17:00 - 17:20

SatE01-02

Profiling japanese EST students' vocabulary ability using the new general service list test (NGSLT) and the new academic word list test (NAWLT)

Shin'ichi Hashimoto	<i>Univ. of Electro-Communications, Japan</i>
Yan Yu	<i>Univ. of Electro-Communications, Japan</i>
Jie Shi	<i>Univ. of Electro-Communications, Japan</i>
Haiyan Zhan	<i>Univ. of Electro-Communications, Japan</i>

17:20 - 17:40

SatE01-03

Peer evaluation of academic presentations by japanese graduate students: qualitative evaluation

Jie Shi	<i>Univ. of Electro-Communications, Japan</i>
Cross John	<i>Univ. of Electro-Communications, Japan</i>

17:40 – 18:00

SatE01-04

Teaching poster by using genre approach to science and technology students of a japanese university

Rajagopalan Maheswari Uma	<i>Toyo Univ., Univ. of Electro-Communications</i>
Jie Shi	<i>Univ. of Electro-Communications, Japan</i>

18:00 – 18:20

SatE01-05

Corpus-based analysis of academic RA Genre: the “Results” sub-genre

Louvigné Sébastien	<i>Univ. of Electro-Communications, Japan</i>
Jie Shi	<i>Univ. of Electro-Communications, Japan</i>

18:20 – 18:40

SatE01-06

Understanding the most essential types of words for Physics undergraduate students

Sonia Sharmin	<i>Univ. of Tsukuba, Japan</i>
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SatE02

Session Room No.02

Information processing

Regular Session

Chair: S.G. Ponnambalam	<i>Monash Univ. Malaysia, Malaysia</i>
Co-Chair: Ken Nakasaka	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

16:40 – 17:00

SatE02-01

Modelling a 20MW scale solar farm in an unused angled area near fukushima nuclear power plant

Amin Mohammadrad	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Ken Nagasaka	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

17:00 – 17:20

SatE02-02

Temporal and spatial projection of wind speed based on modular netrowk SOM for installation of off-shore wind generation

Mitsuharu Hayashi	<i>Tokyo Univ. of Agri. and Tech., Japan</i>
Ken Nagasaka	<i>Tokyo Univ. of Agri. and Tech., Japan</i>

17:20 – 17:40

SatE02-03

A household load priority scheduling model based on real-time electricity price

Bo Hu	<i>State Grid Energy Research Institute, China</i>
Xiao Zhong	<i>North China Electric Power Univ., China</i>
Song Liu	<i>North China Electric Power Univ., China</i>

17:40 – 18:00

SatE02-04

Study on cutting surface stripe and wettability of AZ91D magnesium alloy by WEDM-HS

Jinkai Xu	<i>Changchun Univ. of Sci. and Tech., China</i>
Kui Xia	<i>Changchun Univ. of Sci. and Tech., China</i>
Rongxian Qiu	<i>Changchun Univ. of Sci. and Tech., China</i>
Linshuai Zhang	<i>Changchun Univ. of Sci. and Tech., China</i>
Zhanjiang Yu	<i>Changchun Univ. of Sci. and Tech., China</i>
Huadong Yu	<i>Changchun Univ. of Sci. and Tech., China</i>

18:00 – 18:20

SatE02-05

Influence of microstructure on surface wettability

Xinxin Zhang	<i>Changchun Univ. of Sci. and Tech., China</i>
Jinkai Xu	<i>Changchun Univ. of Sci. and Tech., China</i>
Zhongxu Lian	<i>Changchun Univ. of Sci. and Tech., China</i>
Zhanjiang Yu	<i>Changchun Univ. of Sci. and Tech., China</i>
Huadong Yu	<i>Changchun Univ. of Sci. and Tech., China</i>

SatE03

Session Room No.03

Nonlinear systems modeling control and applications

Organized Session

Organizer: Shiwen Tong *Beijing Union Univ., China*
Chair: Shiwen Tong *Beijing Union Univ., China*
Co-Chair: Dianwei Qian *North China Electric Power Univ., China*

16:40 – 17:00

SatE03-01

Influences from LCL filter on behaviors of Three-phase

Three-level PWM rectifier

Dongsheng Yu *China Univ. of Mining and Tech., China*
Hong Zhu *China Univ. of Mining and Tech., China*
Ciyang Zheng *China Univ. of Mining and Tech., China*

17:00 – 17:20

SatE03-02

Sliding mode output tracking control based on a fuzzy clustering model

Shiwen Tong *Beijing Union Univ., China*
Dianwei Qian *North China Electric Power Univ., China*
Jianjun Fang *Beijing Union Univ., China*

17:20 – 17:40

SatE03-03

PID control of air tank temperature system with parameters tuning through network

Shiwen Tong *Beijing Union Univ., China*
Yushan Li *Beijing Union Univ., China*
Junjie Ren *Beijing Union Univ., China*
Yinong Zhang *Beijing Union Univ., China*

17:40 – 18:00

SatE03-04

Sliding-mode-based disturbance rejection control of nonlinear power systems with renewable sources

Hong Liu *North China Electric Power Univ., China*
Dianwei Qian *North China Electric Power Univ., China*

18:00 – 18:20

SatE03-05

Research and application of predictive control algorithm based on fuzzy model

Yuan Li *Beijing union Univ., China*
Sen Cong *Beijing union Univ., China*
Shiwen Tong *Beijing union Univ., China*
Jianjun Fang *Beijing union Univ., China*

End of the 2nd Day

ICAMechS 2015
Sunday, August 23, 2015

08:50 - 09:50 Main Conference Hall
Plenary Speech 3

Designed to Fail: Incorporating Kinematic Redundancy into Robotic Systems

Anthony A. Maciejewski

Colorado State University, USA

Chair: J. X. Zhang *Swinburne University of Technology, Australia*

09:50 - 10:20 Break

Technical Poster Session

10:20-11:30, Sunday, August 23, 2015

Poster Main Conference Room

Chair: Changan Jiang *Ritsumeikan Univ., Japan*
Xiaoguang Zhou *Beijing Univ. of Posts and Telecommunications, China*
Co-Chair: Shin Wakitani *Tokyo Univ. of Agri. and Tech., Japan*
Yixin Yin *Univ. of Sci. and Tech. Beijing, China*

10:20 – 11:30 **Poster-01**

Bipolar neutrosophic sets and their application based on multi-criteria decision making problems

Irfan Deli *Aralik University, Turkey*
Mumtaz Ali *Quaid-e-azam Univ., Pakistan*
Florentin Smarandache *Univ. of New Mexico, USA*

10:20 – 11:30 **Poster-02**

Evaluation method of main production resource in society and industrial park of extreme arid region (1)

Litifu Zulati *Xinjiang Univ. of Finance and Economics, China*

10:20 – 11:30 **Poster-03**

Research on control methods of permanent magnet synchronous motor position servo system

Fen Yang *Xidian Univ., China*
Zhengfeng Ming *Xidian Univ., China*
Tao Wen *Xidian Univ., China*
Tong Zhang *Xidian Univ., China*
Zhanxia Zhu *Northwestern Polytechnical Univ., China*

10:20 – 11:30 **Poster-04**

Comprehensive functions of eco-industrial park in conserving energy and improving ecology

Litifu Zulati *Xinjiang Univ. of Finance and Economics, China*
Ken Nagasaka *Tokyo Univ. of Agri. and Tech., Japan*

10:20 – 11:30 **Poster-05**

Study on fuzzy-logic PID control system of synchronous jack-up system of turbine runner static equilibrium experiment

Yongxing Hao *North China Univ. of Water Resources and Electric Power, China*
Chaofeng Wang *North China Univ. of Water Resources and Electric Power, China*
Lihui Song *North China Univ. of Water Resources and Electric Power, China*

10:20 – 11:30 **Poster-06**

The straight line mechanism base on peaucellier inversion instrument

Kai He *Beijing Univ. of Posts and Telecommunications, China*
Lei Guo *Beijing Univ. of Posts and Telecommunications, China*
Yuan Song *Beijing Univ. of Posts and Telecommunications, China*

10:20 – 11:30 **Poster-07**

Mechanical design and realization of automatic docking mechanism

Xinhu Mo *Beijing Univ. of Posts and Telecommunications, China*
Lei Guo *Beijing Univ. of Posts and Telecommunications, China*
Yuan Song *Beijing Univ. of Posts and Telecommunications, China*
Ying Zhang *Beijing Univ. of Posts and Telecommunications, China*

10:20 – 11:30 **Poster-08**

Design and implementation of a mechanical calculator for quadratic equation with one unknown

Bin Xing *Beijing Univ. of Posts and Telecommunications, China*
Lei Guo *Beijing Univ. of Posts and Telecommunications, China*
Shimin Wei *Beijing Univ. of Posts and Telecommunications, China*
Yuan Song *Beijing Univ. of Posts and Telecommunications, China*

	<i>Telecommunications, China</i>	
Ying Zhang	<i>Beijing Univ. of Posts and Telecommunications, China</i>	
		10:20 – 11:30
		Poster-09
	A comparative study on inter-tern short circuit fault of PMSM using finite element analysis and experiment	
Yongcan Li	<i>Hebei Univ. of Sci. and Tech., China</i>	
Yongchun Liang	<i>Hebei Univ. of Sci. and Tech., China</i>	
		10:20 – 11:30
		Poster-10
	A research on construction of 30 bus large-scale smart grid model	
Sho Kainose	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
Ken Nagasaka	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
		10:20 – 11:30
		Poster-11
	Modeling a lithium-ion battery based on a threshold model	
Zhi Zhang	<i>Beijing Jiaotong Univ., China</i>	
		10:20 – 11:30
		Poster-12
	Modelling the relationship between constituents and anti-RSV effect of baikal skullcap root	
Ke Li	<i>Shandong Acad. of Sci., China</i>	
Bonian Zhao	<i>Shandong Acad. of Chinese Medicine, China</i>	
Yan Gao	<i>Shandong Acad. of Chinese Medicine, China</i>	
Bianli Wang	<i>Shandong Acad. of Chinese Medicine, China</i>	
Zongyuan Yu	<i>Shandong Acad. of Chinese Medicine, China</i>	
Hongpeng Zhao	<i>Qianfo Mountain Hospital of Shandong Province, China</i>	
		10:20 – 11:30
		Poster-13
	Energy-saving improvement and simulation study on digital hydraulic system	
Fei Song	<i>Naval Univ. of Eng., China</i>	
Jingjun Lou	<i>Naval Univ. of Eng., China</i>	
Likun Peng	<i>Naval Univ. of Eng., China</i>	
		10:20 – 11:30
		Poster-14
	Path planning of airfoil surface for robotic fibre placement	
Lina Li	<i>Chinese Acad. of Sci., China</i>	
Xingang Wang	<i>Chinese Acad. of Sci., China</i>	
De Xu	<i>Chinese Acad. of Sci., China</i>	
Min Tan	<i>Chinese Acad. of Sci., China</i>	
		10:20 – 11:30
		Poster-15
	Strongly stable GPC with suppression of steady state gain and closed-loop poles	
Akira Inoue	<i>Okayama Univ., Japan</i>	
Tomohiro Henmi	<i>National Institute of Tech., Kagawa College, Japan</i>	
Mingcong Deng	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
		10:20 – 11:30
		Poster-16
	Model free fault detection using one set of reference input and output data	
Akira Inoue	<i>Okayama Univ., Japan</i>	
Tomohiro Henmi	<i>National Institute of Tech., Kagawa College, Japan</i>	
Mingcong Deng	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
		10:20 – 11:30
		Poster-17
	Research on algorithm of nonlinear self-adaptive flight control system	
Hao Long	<i>Beijing Union Univ., China</i>	
Shujie Song	<i>Aviation Industry Co. of China, China</i>	
		10:20 – 11:30
		Poster-18
	The indoor real-time 3D localization algorithm using UWB	
Xuehong Li	<i>Univ. of Sci. and Tech. Beijing, China</i>	
Shuhua Yang	<i>Univ. of Sci. and Tech. Beijing, China</i>	
		10:20 – 11:30
		Poster-19
	Operator and sliding mode based nonlinear control for cooling and heat-retention system actuated by Peltier devices	
Takafumi Hatano	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
Mingcong Deng	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
Shin Wakitani	<i>Tokyo Univ. of Agri. and Tech., Japan</i>	
		10:20 – 11:30
		Poster-20
	Control system design for ionic polymer metal composite using a single neuron based adaptive PID approach	
Yiping Chang	<i>Zhongyuan Univ. of Tech., China</i>	
Hui Wang	<i>Zhongyuan Univ. of Tech., China</i>	
		10:20 – 11:30
		Poster-21
	Evaluation method of main production resource of society and industrial park of extreme arid region (2)	
Litifu Zulati	<i>Xinjiang Univ. of Finance and Economics, China</i>	

10:20 – 11:30	Poster-22	Qixian Zhou Tengteng Cui	<i>Henan Univ. of Sci. and Tech., China</i> <i>Henan Univ. of Sci. and Tech., China</i>
Dynamic and energy analysis based on bumper system low-speed collision test			
Zhiming Wang	<i>Shanghai Univ., China</i>		
Li Chen	<i>Shanghai Univ., China</i>		
10:20 – 11:30	Poster-23		
Feasibility of neucube spiking neural network architecture for EMG pattern recognition			
Long Peng	<i>Chinese Acad. of Sci., China</i>		
Zengguang Hou	<i>Chinese Acad. of Sci., China</i>		
Nikola Kasabov	<i>Auckland Univ. of Tech., New Zealand</i>		
Guibin Bian	<i>Chinese Acad. of Sci., China</i>		
Luige Vladareanu	<i>Romanian Acad., Romania</i>		
Hongnian Yu	<i>Bournemouth Univ., UK</i>		
10:20 – 11:30	Poster-24		
Optimal fiber orientations and topology of compliant mechanisms using lamination parameters			
Xinxing Tong	<i>Northwestern Polytechnical Univ., China</i>		
Wenjie Ge	<i>Northwestern Polytechnical Univ., China</i>		
Yonghong Zhang	<i>Northwestern Polytechnical Univ., China</i>		
10:20 – 11:30	Poster-25		
A software platform for interactive analysis on 3D medical data			
Wei Cheng	<i>Shandong Acad. of Sci., China</i>		
Yongfei Xiao	<i>Shandong Acad. of Sci., China</i>		
Youlei Zhao	<i>Taikoo (Shandong) Aircraft Eng. Co., Ltd., China</i>		
10:20 – 11:30	Poster-26		
Master-slave force control based on Grey GM(1,1) Model of robot gripper			
Wei Cheng	<i>Shandong Acad. of Sci., China</i>		
Xuelin Wang	<i>Shandong Acad. of Sci., China</i>		
Haiyan Ma	<i>Shandong Acad. of Sci., China</i>		
10:20 – 11:30	Poster-27		
Remote automatic test system based on MATLAB using VISA over LAN			
Wei Cheng	<i>Shandong Acad. of Sci., China</i>		
Fenggui Wang	<i>Shandong Acad. of Sci., China</i>		
Haiyan Ma	<i>Shandong Acad. of Sci., China</i>		
10:20 – 11:30	Poster-28		
Cubic spline solution for a class of boundary value problems using spectral collocation method			
Tianjun Wang	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-29		
Maximum efficiency control method of permanent magnet synchronous motor based on three-dimensional table			
Gensheng Li	<i>Henan Univ. of Sci. and Tech., China</i>		
Jinfa Xie	<i>Henan Univ. of Sci. and Tech., China</i>		
Liyou Xu	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-30		
Modeling and simulation of hydro-mechanical continuously variable transmission system based on Simscape			
Zhili Zhou	<i>Henan Univ. of Sci. and Tech., China</i>		
Jiazen Zhang	<i>Henan Univ. of Sci. and Tech., China</i>		
Zhiqiang Guo	<i>YTO Group Corporation, China</i>		
Liyou Xu	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-31		
Performance comparison for savonius type wind turbines by numerical analysis approaches			
Lei Song	<i>Henan Univ. of Sci. and Tech., China</i>		
Hongzhao Liu	<i>Xi'an Univ. of Tech., China</i>		
Zongxiao Yang	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-32		
Fuzzy clustering analysis of batch production recipe			
Shanzhong Liu	<i>Henan Univ. of Sci. and Tech., China</i>		
Xiaonan Song	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-33		
Fully discrete subgrid stabilized finite element method for the Darcy-Brinkman equations in Double-Diffusion convection			
Yunzhang Zhang	<i>Henan Univ. of Sci. and Tech., China</i>		
Zhoufeng Wang	<i>Henan Univ. of Sci. and Tech., China</i>		
Qili Tang	<i>Henan Univ. of Sci. and Tech., China</i>		
10:20 – 11:30	Poster-34		
The simplified homogeneous balance method and its application to Whitham-Broer-Kaup-Like equations			
Wei Li	<i>Henan Univ. of Sci. and Tech., China</i>		
Xinrui Wang	<i>Univ. of Chicago, USA</i>		
11:30 - 13:00	Lunch Break		

Early Afternoon Technical Sessions

13:00-14:40, Sunday, August 23, 2015

SunM01

Session Room No.01

Advanced control systems design - theory and applications

Organized Session

Organizer: Shin Wakitani *Tokyo Univ. of Agri. and Tech., Japan*

Takao Sato *Univ. of Hyogo*

Chair: Shiro Masuda *Tokyo Metropolitan Univ., Japan*

Co-Chair: Shin Wakitani *Tokyo Univ. of Agri. and Tech., Japan*

13:00 – 13:20

SunM01-01

Tracking control of quad-rotor helicopters suspended a power supply cable with on-line estimation of disturbances

Hayami Hayakawa *Nagoya Institute of Tech., Japan*

Shogo Obata *Nagoya Institute of Tech., Japan*

Manabu Yamada *Nagoya Institute of Tech., Japan*

13:20 – 13:40

SunM01-02

Multivariable controller design evaluating closed-loop interaction by iterative LMI optimization using frequency response data

Shogo Shinoda *Mie Univ., Japan*

Kazuhiro Yubai *Mie Univ., Japan*

Daisuke Yashiro *Mie Univ., Japan*

Junji Hirai *Mie Univ., Japan*

13:40 – 14:00

SunM01-03

Flow disturbance suppression for a pneumatic vibration isolator using a central pattern generator

Yukinori Nakamura *Tokyo Univ. of Agri. and Tech., Japan*

Daishi Funaki *Tokyo Univ. of Agri. and Tech., Japan*

Mami Kimura *Tokyo Univ. of Agri. and Tech., Japan*

Shinji Wakui *Tokyo Univ. of Agri. and Tech., Japan*

14:00 – 14:20

SunM01-04

Design of a fault tolerant control system using mahalanobis-taguchi(MT) System

Shin Wakitani *Tokyo Univ. of Agri. and Tech., Japan*

Mingcong Deng *Tokyo Univ. of Agri. and Tech., Japan*

14:20 – 14:40

SunM01-05

Data-driven PID gain tuning for unknown impulse disturbance attenuation

Shiro Masuda *Tokyo Metropolitan Univ., Japan*

SunM02

Session Room No.02

Mechatronic systems analysis and control I

Regular Session

Chair: Xinkai Chen

Shibaura Institute of Tech., Japan

Co-Chair: Hongbo Wang

Yanshan Univ., China

13:00 – 13:20

SunM02-01

Size and weight reduction of semicircular duplex manipulator for rescue operation

Soichiro Kimura *Hosei Univ., Japan*

Kazuyuki Ito *Hosei Univ., Japan*

13:20 – 13:40

SunM02-02

Adaptive fault diagnosis for continuous time-delay repetitive system subject to sensor fault

Haigang Zhang *Univ. of Sci. and Tech. Beijing, China*

Sen Zhang *Univ. of Sci. and Tech. Beijing, China*

Yixin Yin *Univ. of Sci. and Tech. Beijing, China*

13:40 – 14:00

SunM02-03

Model identification and adaptive control design for a 6 DOFs manipulator

Weila Ge *Univ. of Electronic Sci. and Tech. of China, China*

Wei He *Univ. of Sci. and Tech. Beijing, China*

Yunchuan Li *Univ. of Maryland College Park, USA*

Chenguang Yang *Plymouth Univ., UK*

14:00 – 14:20

SunM02-04

Precise tracking control for Piezo-actuated stage using inverse compensation and model predictive control

Nguyen Manh Linh *Shibaura Institute of Tech., Japan*

Tran Vu Minh *Shibaura Institute of Tech., Japan*

Xinkai Chen *Shibaura Institute of Tech., Japan*

14:20 – 14:40

SunM02-05

Oscillatory behavior based fault feature extraction for bearing fault diagnosis

Juanjuan Shi *Univ. of Ottawa, Canada*

Ming Liang *Univ. of Ottawa, Canada*

SunM03

Session Room No.03

Complex systems control and applications I

Regular Session

Chair: Ni Bu

Qingdao Univ. of Sci. and Tech., China

Co-Chair: Zhengfeng Ming

Xidian Univ., China

13:00 – 13:20

SunM03-01

Switched reluctance motor/generator simulation research based

on compressed air energy storage system

Xiaoshu Zan	<i>China Univ. of Mining and Tech., China</i>
Hong Zhu	<i>China Univ. of Mining and Tech., China</i>

13:20 – 13:40

SunM03-02

Surface flaws detection algorithms for large aperture optical element

Zhengtao Zhang	<i>Chinese Acad. of Sci., China</i>
De Xu	<i>Chinese Acad. of Sci., China</i>
Xian Tao	<i>Chinese Acad. of Sci., China</i>
Feng Zhang	<i>Chinese Acad. of Sci., China</i>

13:40 – 14:00

SunM03-03

An adaptive observer-based fault detection and diagnosis for nonlinear systems with sensor and actuator faults

Xiaomo Yan	<i>Univ. of Manchester, UK</i>
Bailing Tian	<i>Tianjing Univ., China</i>
Hong Wang	<i>Univ. of Manchester, UK</i>

14:00 – 14:20

SunM03-04

Minimum mutual information control for multi-variable non-Gaussian stochastic systems

Qichun Zhang	<i>Univ. of Manchester, UK</i>
Aiping Wang	<i>Anhui Univ., China</i>
Hong Wang	<i>Univ. of Manchester, UK</i>

14:20 – 14:40

SunM03-05

Design and simulation of dual fuzzy self-adjusting immune PID controller for grain drying system

Aini Dai	<i>Beijing Univ. of Posts and Telecommunications, China</i>
Xiaoguang Zhou	<i>Beijing Univ. of Posts and Telecommunications, China</i>
Chi Zhang	<i>Beijing Univ. of Posts and Telecommunications, China</i>
Xiangdong Liu	<i>Beijing Univ. of Posts and Telecommunications, China</i>
Huiling Zhou	<i>Beijing Univ. of Posts and Telecommunications, China</i>

14:40 - 14:50**Break****Middle Afternoon Technical Sessions****14:50-16:50, Sunday, August 23, 2015****SunP01**

Session Room No.01

Control of mechatronic systems II

Regular Session

Chair: Changan Jiang	<i>Ritsumeikan Univ., Japan</i>
Co-Chair: Junming Xiao	<i>Zhongyan Univ. of Tech., China</i>

14:50 – 15:10

SunP01-01

A brushless DC motor speed control system based on DSP controller

Songming Cao

Beijing Univ. of Posts and Telecommunications, China

Yong Liu

Beijing Univ. of Posts and Telecommunications, China

Ming Hu

Beijing Univ. of Posts and Telecommunications, China

Xin Fu

Beijing Univ. of Posts and Telecommunications, China

13:20 – 13:40

SunM03-02

15:10 – 15:30

SunP01-02

Precision size measurement instrument for irregular objects

Wanji Liu

SIPO, China

Xian Tao

Chinese Acad. of Sci., China

13:40 – 14:00

SunM03-03

A new method of periodicity estimation for mechanical acoustic data

Zhipan Hong

Shandong Univ., China

Guoliang Lu

Shandong Univ., China

14:00 – 14:20

SunM03-04

15:30 – 15:50

SunP01-03

Acoustic emission signal harr wavelet denoise research

Kenan Shen

Southwest Forestry Univ., China

Mingcong Deng

Tokyo Univ. of Agri. and Tech., Japan

Ming Li

Southwest Forestry Univ., China

14:20 – 14:40

SunM03-05

15:50 – 16:10

SunP01-04

Acoustic emission signal harr wavelet denoise research

Tomohito Hanawa

Tokyo Univ. of Agri. and Tech., Japan

Mingcong Deng

*Tokyo Univ. of Agri. and Tech., Japan***14:40 - 14:50****Break****SunP02**

Session Room No.02

Mechatronic systems analysis and control II

Regular Session

Chair: Shengjun Wen

Zhongyuan Univ. of Tech., China

Co-Chair: Dongyun Wang

Zhongyuan Univ. of Tech., China

14:50 – 15:10

16:10 – 16:30

SunP01-05

Operator-based nonlinear networked control system with packet error

Tomohito Hanawa

Tokyo Univ. of Agri. and Tech., Japan

Mingcong Deng

Tokyo Univ. of Agri. and Tech., Japan

14:20 – 14:40

SunM03-05

16:30 – 16:50

SunP01-06

Optimal control of non-prehensile manipulation control by two cooperative arms

Changan Jiang

Ritsumeikan Univ., Japan

Satoshi Ueno

Ritsumeikan Univ., Japan

Yoshikazu Hayakawa

*Nagoya Univ., Japan***SunP01**

Session Room No.01

Control of mechatronic systems II

Regular Session

Chair: Changan Jiang	<i>Ritsumeikan Univ., Japan</i>
Co-Chair: Junming Xiao	<i>Zhongyan Univ. of Tech., China</i>

14:50 – 15:10

SunP01-01

14:50 – 15:10

SunP02-01

SVR-based input-output mapping of a micro-hand

Kou Fujita

Tokyo Univ. of Agri. and Tech., Japan

Shuichi Wakimoto

Okayama Univ., Japan

Mingcong Deng

Tokyo Univ. of Agri. and Tech., Japan

Shin Wakitani

Tokyo Univ. of Agri. and Tech., Japan

15:10 – 15:30	SunP02-02	Yong Liu Ming Hu Songming Cao	<i>Beijing Univ. of Posts and Telecommunications, China</i> <i>Beijing Univ. of Posts and Telecommunications, China</i> <i>Beijing Univ. of Posts and Telecommunications, China</i>
Nonlinear remote temperature control of a spiral plate heat exchanger			
Ryohei Fujii Mingcong Deng Shin Wakitani	<i>Tokyo Univ. of Agri. and Tech., Japan</i> <i>Tokyo Univ. of Agri. and Tech., Japan</i> <i>Tokyo Univ. of Agri. and Tech., Japan</i>		
15:30 – 15:50	SunP02-03	15:10 – 15:30	SunP03-02
Operator based voltage control experiments of thermoelectric generation system		IPMC robust nonlinear tracking control design based on a multi-objective particle swarm optimization-based RRCF approach	
Ryuji Yoshida Mingcong Deng Shin Wakitani	<i>Tokyo Univ. of Agri. and Tech., Japan</i> <i>Tokyo Univ. of Agri. and Tech., Japan</i> <i>Tokyo Univ. of Agri. and Tech., Japan</i>	Wudai Liao Tongbin Yan Aihui Wang Yiwen Fu	<i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i>
15:50 – 16:10	SunP02-04	15:30 – 15:50	SunP03-03
Robust controller design for networked control system with packet dropout and quantization error		Robot arm with micro-hand robust control design using operator-based robust right coprime factorization approach	
Haiquan Wang Rongxiang Gao Qian Zhang Shengjun Wen	<i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i>	Aihui Wang Hongnian Yu Dongyun Wang Mingcong Deng	<i>Zhongyuan Univ. of Tech., China</i> <i>Bournemouth Univ., UK</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Tokyo Univ. of Agri. and Tech., Japan</i>
16:10 – 16:30	SunP02-05	15:50 – 16:10	SunP03-04
Active power filter design for improving power quality		Complex event processing on uncertain data streams in product manufacturing process	
Junming Xiao Xiangming Zhang Shengjun Wen Zhengbo Liu	<i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i>	Na Mao Jie Tan	<i>Chinese Acad. of Sci., China</i> <i>Chinese Acad. of Sci., China</i>
16:30 – 16:50	SunP02-06	16:10 – 16:30	SunP03-05
Fractional PID based stability control for a single link rotary inverted pendulum		Detecting cracks on a concrete surface using histogram of oriented gradients	
Wudai Liao Zhengbo Liu Shengjun Wen Shuhui Bi Dongyun Wang	<i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Zhongyuan Univ. of Tech., China</i> <i>Univ. of Jinan, China</i> <i>Zhongyuan Univ. of Tech., China</i>	Lin Meng Zhongkui Wang Yoshiyuki Fujikawa Shigeru Oyanagi	<i>Ritsumeikan Univ., Japan</i> <i>Ritsumeikan Univ., Japan</i> <i>Ritsumeikan Univ., Japan</i> <i>Ritsumeikan Univ., Japan</i>
14:50 – 15:10	SunP03-01	16:30 – 16:50	SunP03-06
Design of the automatic sample preparation system		Power balance control for switched reluctance generator integrated in DC microgrid	
Xin Fu Shimin Wei	<i>Beijing Univ. of Posts and Telecommunications, China</i> <i>Beijing Univ. of Posts and Telecommunications, China</i>	T. Wang D. He Q. Wang Y. Huo L. Lu J. Li	<i>Lanzhou Institute of Physics and National Key Lab. of Vacuum and Cryogenic, China</i> <i>Lanzhou Institute of Physics and National Key Lab. of Vacuum and Cryogenic, China</i> <i>China Univ. of Mining and Tech., China</i> <i>Lanzhou Institute of Physics and National Key Lab. of Vacuum and Cryogenic, China</i> <i>China Univ. of Mining and Tech., China</i> <i>China Univ. of Mining and Tech., China</i>

SunP03 Session Room No.03

Complex systems control and applications II

Regular Session

Chair: Aihui Wang *Zhongyuan Univ. of Tech., China*
Co-Chair: Hong Wang *Univ. of Manchester, UK*

14:50 – 15:10	SunP03-01	
Design of the automatic sample preparation system		

16:50 - 17:00 **Break**

17:00 - 18:00

Plenary Panel Discussion

New Developments in Advanced Mechatronic Systems

Speaker: Mingcong Deng *Tokyo Univ. of Agri. and Tech., Japan*
Hongnian Yu *Bournemouth Univ., UK*

18:30 - 20:30

Banquet

(Beijing Fujian Hotel, Beijing)

End of the 3rd Day

ICAMechS 2015
Monday, August 24, 2015

Technical Tour to The Great Wall of China

End of the Conference
